## Functional Safety Information

# DRV8243-Q1 H-Bridge Driver Functional Safety FIT Rate, FMD and Pin FMA



#### **Table of Contents**

1 Overview	2
2 Functional Safety Failure In Time (FIT) Rates	
3 Failure Mode Distribution (FMD)	
4 Pin Failure Mode Analysis (Pin FMA)	
4.1 SPI "S" and "P" variant in HVSSOP package	
4.2 SPI "S" variant in VQFN-HR package	
4.3 HW variant in HVSSOP package	
4.4 HW variant in VQFN-HR package	
5 Revision History	20

#### **Trademarks**

All trademarks are the property of their respective owners.

**STRUMENTS** Overview www.ti.com

#### 1 Overview

This document contains information for DRV8243-Q1 to aid in a functional safety system design. This document covers all the device package and interface variants as listed below:

- HW variant in HVSSOP package
- SPI "S" variant in HVSSOP package
- SPI "P" variant in HVSSOP package
- HW variant in VQFN-HR package
- SPI "S" variant in VQFN-HR package

#### Information provided are:

- Functional Safety Failure In Time (FIT) rates of the semiconductor component estimated by the application of industry reliability standards
- Component failure modes and their distribution (FMD) based on the primary function of the device
- Pin failure mode analysis (Pin FMA) for all the package and interface variants

Figure 1-1 shows the HW device variant's functional block diagram for reference.

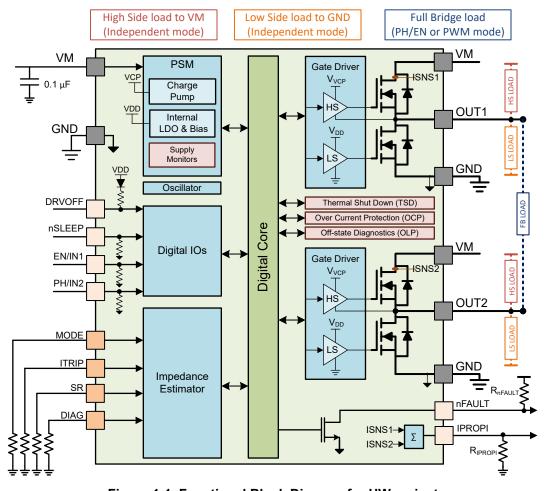


Figure 1-1. Functional Block Diagram for HW variant

Figure 1-2 shows the SPI "S" device variant's functional block diagram for reference.

www.ti.com Overview

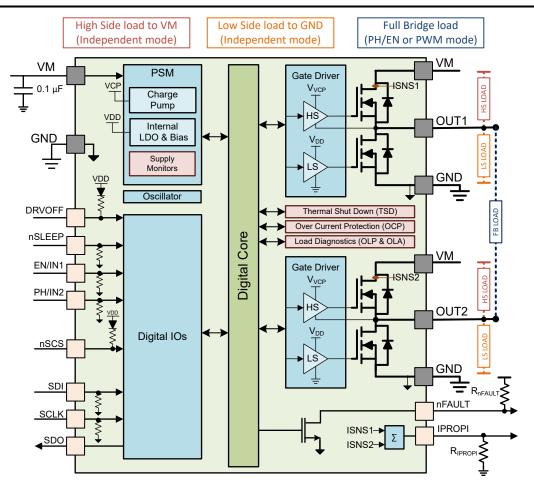


Figure 1-2. Functional Block Diagram for SPI "S" variant

Figure 1-3 shows the SPI "P" device variant's functional block diagram for reference.

Overview INSTRUMENTS

www.ti.com

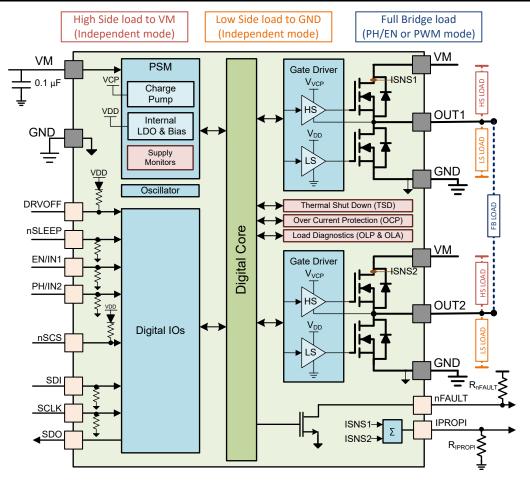


Figure 1-3. Functional Block Diagram for SPI "P" variant

DRV8243-Q1 was developed using a quality-managed development process, but was not developed in accordance with the IEC 61508 or ISO 26262 standards.

ADVANCE INFORMATION for preproduction products; subject to change without notice.

## 2 Functional Safety Failure In Time (FIT) Rates

This section provides Functional Safety Failure In Time (FIT) rates for DRV8243-Q1 based on two different industry-wide used reliability standards:

- Table 2-1 provides FIT rates based on IEC TR 62380 / ISO 26262 part 11
- Table 2-2 provides FIT rates based on the Siemens Norm SN 29500-2

Table 2-1. Component Failure Rates per IEC TR 62380 / ISO 26262 Part 11

FIT IEC TR 62380 /		FIT	์ (Failures Per 10 <sup>9</sup> Hoเ	ırs)	
ISO 26262	HW variant in HVSSOP package	SPI "S" variant in HVSSOP package	SPI "P" variant in HVSSOP package	HW variant in VQFN- HR package	SPI "S" variant in VQFN-HR package
Total Component FIT Rate	23	23	23	26	26
Die FIT Rate	9	9	9	16	16
Package FIT Rate	14	14	14	10	10

The failure rate and mission profile information in Table 2-1 comes from the Reliability data handbook IEC TR 62380 / ISO 26262 part 11:

Mission Profile: Motor Control from Table 11

Power dissipation: 1150 mW
Climate type: World-wide Table 8
Package factor (lambda 3): Table 17b

Substrate Material: FR4EOS FIT rate assumed: 0 FIT

Table 2-2. Component Failure Rates per Siemens Norm SN 29500-2

Table	Category	Reference FIT Rate	Reference Virtual T <sub>J</sub>
5	CMOS,BICMOS Digital, analog / mixed	25 FIT	55°C

The Reference FIT Rate and Reference Virtual T<sub>J</sub> (junction temperature) in Table 2-2 come from the Siemens Norm SN 29500-2 tables 1 through 5. Failure rates under operating conditions are calculated from the reference failure rate and virtual junction temperature using conversion information in SN 29500-2 section 4.



## 3 Failure Mode Distribution (FMD)

The failure mode distribution estimation for DRV8243-Q1 in Table 3-1 comes from the combination of common failure modes listed in standards such as IEC 61508 and ISO 26262, the ratio of sub-circuit function size and complexity and from best engineering judgment.

The failure modes listed in this section reflect random failure events and do not include failures due to misuse or overstress.

Table 3-1. Die Failure Modes and Distribution

Die Failure Modes	Failure Mode Distribution (%)
Output is stuck LOW when commanded OFF (GND short)	14% <sup>(2)</sup>
Output is stuck HIGH when commanded OFF (VM short)	14% <sup>(2)</sup>
Output is stuck OFF when commanded LOW (Open)	8%(2)
Output is stuck OFF when commanded HIGH (Open)	8%(2)
Output ON resistance too high when commanded LOW	12% <sup>(2)</sup>
Output ON resistance too high when commanded HIGH	18% <sup>(2)</sup>
Low side slew rate too fast or too slow (high-side recirculation)	5% <sup>(2)</sup>
High side slew rate too fast or too slow (low-side recirculation)	5% <sup>(2)</sup>
Dead-time is too short	1%(2)
Current sense feedback incorrect	3%
ITRIP current regulation incorrect	3%
Incorrect communication (SPI variant)/ configuration interpretation (HW variant)	4%(1)
Incorrect input interpretation (nSLEEP, DRVOFF, EN/IN1, PH/IN2)	4%(1)
Incorrect nFAULT assertion	1%

<sup>(1) 1%</sup> for each pin function

<sup>(2) 50%</sup> for OUT1, 50% for OUT2



## 4 Pin Failure Mode Analysis (Pin FMA)

This section provides a Failure Mode Analysis (FMA) of the pins for each of the device variants of DRV8243-Q1 as listed below.

- 1. HW variant in HVSSOP package
- 2. SPI "S" variant in HVSSOP package
- 3. SPI "P" variant in HVSSOP package
- 4. HW variant in VQFN-HR package
- 5. SPI "S" variant in VQFN-HR package

The failure modes covered in this document include the typical pin-by-pin failure scenarios:

- · Pin short-circuited to Ground
- · Pin open-circuited
- Pin short-circuited to an adjacent pin
- · Pin short-circuited to supply

The analysis also indicates how these pin conditions can affect the device as per the failure effects classification in Table 4-1.

Table 4-1. TI Classification of Failure Effects

Class	Failure Effects
А	Potential device damage that affects functionality
В	No device damage, but loss of functionality
С	No device damage, but performance degradation
D	No device damage, no impact to functionality or performance



Following are the assumptions of use and the device configuration assumed for the pin FMA in this section:

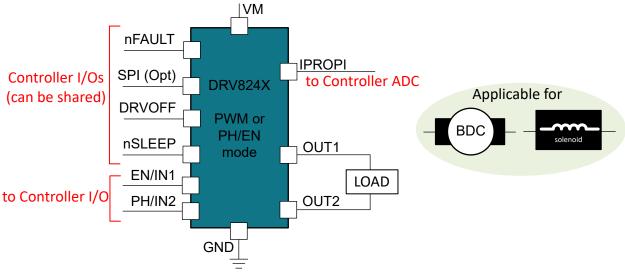


Figure 4-1. DRV824x-Q1 in Full Bridge mode

- · Test conditions:
  - V<sub>VM</sub> = 13.5 V, T<sub>Ambient</sub> = 25°C , SPI "P" variant: V<sub>VDD</sub> = 5 V
- SPI "S" and "P" variant:
  - DRVOFF, EN/IN1 pins controlled by controller, PH/IN2 pin tied low
  - IPROPI pin monitored by controller, nFAULT pin monitoring optional
  - Configurations: PH/EN mode, SPI\_IN unlocked with
    - DRVOFF\_SEL = 1'b0 (Pin and register control for redundant shutoff)
    - EN\_IN1\_SEL = 1'b1 (Pin only control for PWM)
    - PH\_IN2\_SEL = 1'b0 (Register only control for direction)
- HW variant:
- nSLEEP, DRVOFF, EN/IN1, PH/IN2 pins controlled by controller
  - nFAULT and IPROPI pins monitored by controller
  - Configuration: PWM mode

## 4.1 SPI "S" and "P" variant in HVSSOP package

Figure 4-2 shows the pin diagram. For a detailed description of the device pins please refer to the *Pin Configuration and Functions* section in the DRV8243-Q1 data sheet.

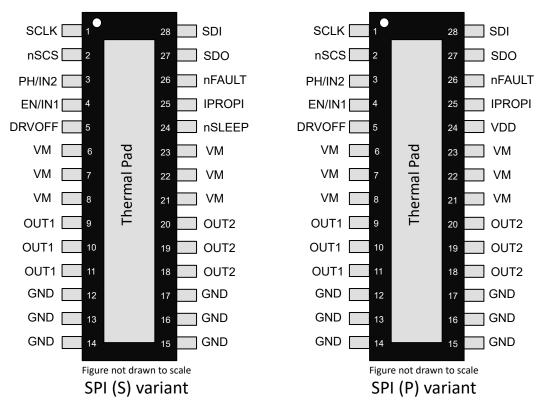


Figure 4-2. SPI "S" and "P" variants

Table 4-2. Pin FMA for Device Pins Short-Circuited to Ground

Pi	in		
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	SCLK	SPI communication is lost.	В
2	nSCS	SPI communication is lost.	В
3	PH/IN2	Normal function as register bit is used for direction control.	D
4	EN/IN1	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
5	DRVOFF	Pin based shutoff function is lost.	В
6, 7, 8, 21, 22, 23	VM	Device is powered off with driver Hi-Z.	В
9, 10, 11	OUT1	If OUT1 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
12, 13, 14, 15, 16, 17	GND	Normal function.	D
18, 19, 20	OUT2	If OUT2 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
24	nSLEEP	Deth "C" 9 "D" variants, Device will be in CLEED state and outputs are 11.7	В
24	VDD	Both "S" & "P" variants: Device will be in SLEEP state and outputs are Hi-Z.	Б
25	IPROPI	IPROPI feedback is lost. ITRIP regulation, if enabled, is also lost.	В
26	nFAULT	False fault signalling possible. Device will continue to operate as commanded.	В
27	SDO	SPI communication is lost.	В
28	SDI	SPI communication is lost.	В



#### Table 4-3. Pin FMA for Device Pins Open-Circuited

P	in		
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	SCLK	SPI communication is lost.	В
2	nSCS	SPI communication is lost.	В
3	PH/IN2	Normal function as register bit is used for direction control.	D
4	EN/IN1	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
5	DRVOFF	Pin based shutoff is triggered and outputs are Hi-Z.	В
6, 7, 8, 21, 22, 23	VM	Device is powered off with driver Hi-Z.	В
9, 10, 11	OUT1	Load drive capability is lost.	В
12, 13, 14, 15, 16, 17	GND	Device is powered off with driver Hi-Z.	В
18, 19, 20	OUT2	Load drive capability is lost.	В
24	nSLEEP	Dath "C" 9 "D" variants. Davisa will be in SI FFD state and outsute are Hi 7	В
24	VDD	Both "S" & "P" variants: Device will be in SLEEP state and outputs are Hi-Z.	В
25	IPROPI	IPROPI feedback is lost. Load will be forced to recirculate if ITRIP regulation is enabled.	В
26	nFAULT	False fault signaling possible. Device will continue to operate as commanded.	В
27	SDO	SPI communication is lost.	В
28	SDI	SPI communication is lost.	В

#### Table 4-4. Pin FMA for Device Pins Short-Circuited to Adjacent Pin

Short bet	ween pins	Description of Potential Failure Effect(s)	Failure Effect Class
SCLK	SDI	SPI communication is lost.	В
nSCS	SCLK	SPI communication is lost.	В
PH/IN2	nSCS	Normal function as register bit is used for direction control.	D
EN/IN1	PH/IN2	External PWM control is lost. Internal ITRIP regulation is OK. No risk of spin direction reversal.	D
DRVOFF	EN/IN1	Outputs are either Hi-Z or load is in re-circulation state.	В
VM	DRVOFF	Outputs are Hi-Z.	В
OUT1	VM	If OUT1 is commanded to be pulled low, short is detected and outputs are Hi-Z	В
GND	OUT1	If OUT1 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
OUT2	GND	If OUT2 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
VM	OUT2	If OUT2 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
nSLEEP		"S" variant: SLEEP functionality is lost	В
VDD	VM	"P" variant: Device damage possible. Device behavior can not be guaranteed.	Α
IPROPI	nSLEEP	"S" variant: IPROPI feedback is inaccurate. ITRIP regulation levels, if enabled, will be lower.	В
IFKOFI	VDD	"P" variant: IPROPI feedback is inaccurate. Outputs are Hi-Z if ITRIP regulation is enabled.	Ь
nFAULT	IPROPI	False fault signaling possible. IPROPI feedback is inaccurate. ITRIP regulation levels, if enabled, will be lower.	В
SDO	nFAULT	False fault signaling possible. SPI communication will be affected during fault assertion.	В
SDI	SDO	SPI communication is lost.	В

#### Table 4-5. Pin FMA for Device Pins Short-Circuited to supply VM

		11 9	
P	in	Description of Potential Failure Effect(s)	Failure
No.	Name		Effect Class
1	SCLK	Device damage possible.	Α



Table 4-5. Pin FMA for Device Pins Short-Circuited to supply VM (continued)

Pi	in		
No.	Name	Description of Potential Failure Effect(s)	Effect Class
2	nSCS	Device damage possible.	Α
3	PH/IN2	Device damage possible.	Α
4	EN/IN1	Device damage possible.	Α
5	DRVOFF	Outputs are Hi-Z.	В
6, 7, 8, 21, 22, 23	VM	Normal function.	D
9, 10, 11	OUT1	If OUT1 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
12, 13, 14, 15, 16, 17	GND	Device is powered off with driver Hi-Z.	В
18, 19, 20	OUT2	If OUT2 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
24	nSLEEP	"S" variant: SLEEP functionality is lost.	В
24	VDD	"P" variant: Device damage possible.	Α
25	IPROPI	Device damage possible.	Α
26	nFAULT	Device damage possible.	Α
27	SDO	Device damage possible.	Α
28	SDI	Device damage possible.	Α



#### 4.2 SPI "S" variant in VQFN-HR package

Figure 4-3shows the pin diagram. For a detailed description of the device pins please refer to the *Pin Configuration and Functions* section in the DRV8243-Q1 data sheet.

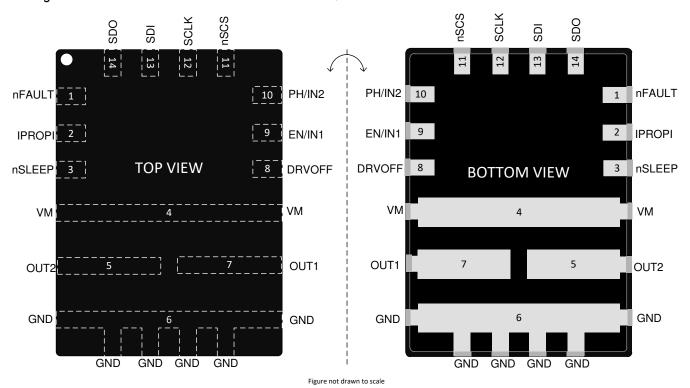


Figure 4-3. SPI "S" variant

Table 4-6. Pin FMA for Device Pins Short-Circuited to Ground

P	in		
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	nFAULT	False fault signalling possible. Device will continue to operate as commanded.	В
2	IPROPI	IPROPI feedback is lost. ITRIP regulation, if enabled, is also lost.	В
3	nSLEEP	Device will be in SLEEP state and outputs are Hi-Z.	В
4	VM	Device is powered off with driver Hi-Z.	В
5	OUT2	If OUT2 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
6	GND	Normal function.	D
7	OUT1	If OUT1 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
8	DRVOFF	Pin based shutoff function is lost.	В
9	EN/IN1	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
10	PH/IN2	Normal function as register bit is used for direction control.	D
11	nSCS	SPI communication is lost.	В
12	SCLK	SPI communication is lost.	В
13	SDI	SPI communication is lost.	В
14	SDO	SPI communication is lost.	В

Table 4-7. Pin FMA for Device Pins Open-Circuited

P	in	Description of Potential Failure Effect(s)	Failure
No.	Name		Effect Class
1	nFAULT	False fault signaling possible. Device will continue to operate as commanded.	В



Table 4-7. Pin FMA for Device Pins Open-Circuited (continued)

Pin			Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
2	IPROPI	IPROPI feedback is lost. Load will be forced to recirculate if ITRIP regulation is enabled.	В
3	nSLEEP	Device will be in SLEEP state and outputs are Hi-Z.	В
4	VM	Device is powered off with driver Hi-Z.	В
5	OUT2	Load drive capability is lost.	В
6	GND	Device is powered off with driver Hi-Z.	В
7	OUT1	Load drive capability is lost.	В
8	DRVOFF	Pin based shutoff is triggered and outputs are Hi-Z.	В
9	EN/IN1	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
10	PH/IN2	Normal function as register bit is used for direction control.	D
11	nSCS	SPI communication is lost.	В
12	SCLK	SPI communication is lost.	В
13	SDI	SPI communication is lost.	В
14	SDO	SPI communication is lost.	В

Table 4-8. Pin FMA for Device Pins Short-Circuited to Adjacent Pin

Short bet	ween pins	Description of Potential Failure Effect(s)	Failure Effect Class
nFAULT	SDO	False fault signaling possible. SPI communication will be affected during fault assertion.	В
IPROPI	nFAULT	False fault signaling possible. IPROPI feedback is inaccurate. ITRIP regulation levels, if enabled, will be lower.	В
nSLEEP	IPROPI	IPROPI feedback is inaccurate. ITRIP regulation levels, if enabled, will be lower.	В
VM	nSLEEP	SLEEP functionality is lost.	В
OUT2	VM	If OUT2 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
GND	OUT2	If OUT2 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
OUT1	GND	If OUT1 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
VM	OUT1	If OUT1 is commanded to be pulled low, short is detected and outputs are Hi-Z	В
DRVOFF	VM	Outputs are Hi-Z.	В
EN/IN1	DRVOFF	Outputs are either Hi-Z or load is in re-circulation state.	В
PH/IN2	EN/IN1	External PWM control is lost. Internal ITRIP regulation is OK. No risk of spin direction reversal.	D
nSCS	PH/IN2	Normal function as register bit is used for direction control.	D
SCLK	nSCS	SPI communication is lost.	В
SDI	SCLK	SPI communication is lost.	В
SDO	SDI	SPI communication is lost.	В



#### Table 4-9. Pin FMA for Device Pins Short-Circuited to VM

Pin			Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	nFAULT	Device damage possible.	Α
2	IPROPI	Device damage possible.	Α
3	nSLEEP	SLEEP functionality is lost.	В
4	VM	Normal function.	D
5	OUT2	If OUT2 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
6	GND	Device is powered off with driver Hi-Z.	В
7	OUT1	If OUT1 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
8	DRVOFF	Outputs are Hi-Z.	В
9	EN/IN1	Device damage possible.	Α
10	PH/IN2	Device damage possible.	Α
11	nSCS	Device damage possible.	Α
12	SCLK	Device damage possible.	Α
13	SDI	Device damage possible.	Α
14	SDO	Device damage possible.	Α



#### 4.3 HW variant in HVSSOP package

Figure 4-4 shows the pin diagram. For a detailed description of the device pins please refer to the *Pin Configuration and Functions* section in the DRV8243-Q1 data sheet.

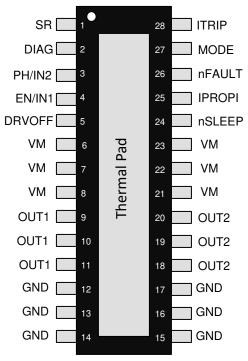


Figure not drawn to scale

Figure 4-4. HW variant

Table 4-10. Pin FMA for Device Pins Short-Circuited to Ground

P	in		Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	SR	Wrong SR configuration possible, EM performance may be affected.	В
2	DIAG	Wrong load and fault response configuration possible.	В
3	PH/IN2	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
4	EN/IN1	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
5	DRVOFF	Shutoff function is lost.	В
6, 7, 8, 21, 22, 23	VM	Device is powered off with driver Hi-Z.	В
9, 10, 11	OUT1	If OUT1 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
12, 13, 14, 15, 16, 17	GND	Normal function.	D
18, 19, 20	OUT2	If OUT2 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
24	nSLEEP	Device will be in SLEEP state and outputs are Hi-Z.	В
25	IPROPI	IPROPI feedback is lost. ITRIP regulation, if enabled, is also lost.	В
26	nFAULT	False fault signalling possible. Device will continue to operate as commanded.	В
27	MODE	Wrong MODE configuration possible.	В
28	ITRIP	Incorrect ITRIP level for current regulation possible.	В

Table 4-11. Pin FMA for Device Pins Open-Circuited

Pin			Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	SR	Wrong SR configuration, EM performance may be affected.	В
2	DIAG	Wrong load and fault response configuration possible.	В



**Table 4-11. Pin FMA for Device Pins Open-Circuited (continued)** 

rable 4 11.1 mr mix for bevice 1 mb open encured (continued)			
P No.	in Name	Description of Potential Failure Effect(s)	Failure Effect Class
3	PH/IN2	Normal function as register bit is used for direction control.	D
4	EN/IN1	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
5	DRVOFF	Pin based shutoff is triggered and outputs are Hi-Z.	В
6, 7, 8, 21, 22, 23	VM	Device is powered off with driver Hi-Z.	В
9, 10, 11	OUT1	Load drive capability is lost.	В
12, 13, 14, 15, 16, 17	GND	Device is powered off with driver Hi-Z.	В
18, 19, 20	OUT2	Load drive capability is lost.	В
24	nSLEEP	Device will be in SLEEP state and outputs are Hi-Z.	В
25	IPROPI	IPROPI feedback is lost. Load will be forced to recirculte if ITRIP regulation is enabled.	В
26	nFAULT	False fault signalling. Device will continue to operate as commanded.	В
27	MODE	Normal function.	D
28	ITRIP	Incorrect ITRIP level for current regulation possible.	В

Table 4-12. Pin FMA for Device Pins Short-Circuited to Adjacent Pin

Short bet	ween pins	Description of Potential Failure Effect(s)	Failure Effect Class
SR	ITRIP	Wrong configuration - EM performance may be affected. Incorrect ITRIP level for current regulation possible.	В
DIAG	SR	Wrong configuration - EM performance may be affected. Load and fault response may be incorrect.	В
PH/IN2	DIAG	Normal function as register bit is used for direction control.	D
EN/IN1	PH/IN2	External PWM control is lost. Internal ITRIP regulation is OK. No risk of spin direction reversal.	D
DRVOFF	EN/IN1	Outputs are either Hi-Z or load is in re-circulation state.	В
VM	DRVOFF	Outputs are Hi-Z.	В
OUT1	VM	If OUT1 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
GND	OUT1	If OUT1 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
OUT2	GND	If OUT2 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
VM	OUT2	If OUT2 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
nSLEEP	VM	SLEEP functionality is lost.	В
IPROPI	nSLEEP	IPROPI feedback is inaccurate. ITRIP regulation levels, if enabled, will be lower.	В
nFAULT	IPROPI	False fault signaling possible. IPROPI feedback is inaccurate. ITRIP regulation levels, if enabled, will be lower.	В
MODE	nFAULT	False fault signaling possible. MODE setting is not affected.	В
ITRIP	MODE	Wrong configuration possible- Both MODE and ITRIP settings are affected.	В



#### Table 4-13. Pin FMA for Device Pins Short-Circuited to VM

Pin			Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	SR	Device damage possible.	Α
2	DIAG	Device damage possible.	Α
3	PH/IN2	Device damage possible.	Α
4	EN/IN1	Device damage possible.	Α
5	DRVOFF	Outputs are Hi-Z.	В
6, 7, 8, 21, 22, 23	VM	Normal function.	D
9, 10, 11	OUT1	If OUT1 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
12, 13, 14, 15, 16, 17	GND	Device is powered off with driver Hi-Z.	В
18, 19, 20	OUT2	If OUT2 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
24	nSLEEP	SLEEP functionality is lost.	В
25	IPROPI	Device damage possible.	Α
26	nFAULT	Device damage possible.	Α
27	MODE	Device damage possible.	Α
28	ITRIP	Device damage possible.	Α



#### 4.4 HW variant in VQFN-HR package

Figure 4-5shows the pin diagram. For a detailed description of the device pins please refer to the *Pin Configuration and Functions* section in the DRV8243-Q1 data sheet.

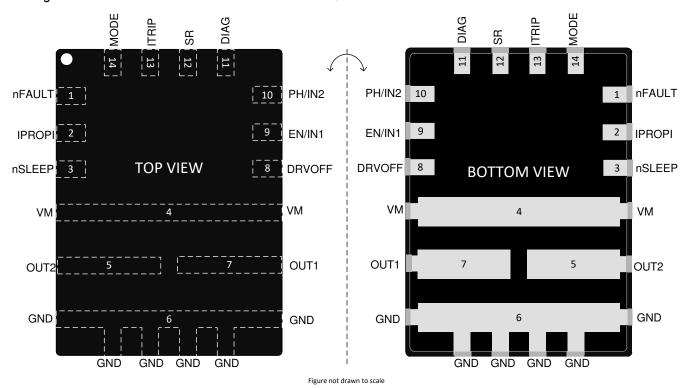


Figure 4-5. HW variant

Table 4-14. Pin FMA for Device Pins Short-Circuited to Ground

Pin			Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	nFAULT	False fault signalling possible. Device will continue to operate as commanded.	В
2	IPROPI	IPROPI feedback is lost. ITRIP regulation, if enabled, is also lost.	В
3	nSLEEP	Device will be in SLEEP state and outputs are Hi-Z.	В
4	VM	Device is powered off with driver Hi-Z.	В
5	OUT2	If OUT2 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
6	GND	Normal function.	D
7	OUT1	If OUT1 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
8	DRVOFF	Shutoff function is lost.	В
9	EN/IN1	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
10	PH/IN2	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
11	DIAG	Wrong load and fault response configuration possible.	В
12	SR	Wrong SR configuration possible, EM performance may be affected.	В
13	ITRIP	Incorrect ITRIP level for current regulation possible.	В
14	MODE	Wrong MODE configuration possible.	В

Table 4-15. Pin FMA for Device Pins Open-Circuited

Pin			Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	nFAULT	False fault signalling possible. Device will continue to operate as commanded.	В

Table 4-15. Pin FMA for Device Pins Open-Circuited (continued)

F	Pin		Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
2	IPROPI	IPROPI feedback is lost. Load will be forced to recirculte if ITRIP regulation is enabled.	В
3	nSLEEP	Device will be in SLEEP state and outputs are Hi-Z.	В
4	VM	Device is powered off with driver Hi-Z.	В
5	OUT2	Load drive capability is lost.	В
6	GND	Device is powered off with driver Hi-Z.	В
7	OUT1	Load drive capability is lost.	В
8	DRVOFF	Pin based shutoff is triggered and outputs are Hi-Z.	В
9	EN/IN1	Load will be in re-circulation (braking). No risk of spin direction reversal.	В
10	PH/IN2	Normal function as register bit is used for direction control.	D
11	DIAG	Wrong load and fault response configuration possible.	В
12	SR	Wrong SR configuration possible, EM performance may be affected.	В
13	ITRIP	Incorrect ITRIP level for current regulation possible.	В
14	MODE	Normal function.	D

Table 4-16. Pin FMA for Device Pins Short-Circuited to Adjacent Pin

Table 4-16. Fill FMA for Device Fills Short-Circuited to Adjacent Fill			
Short bet	ween pins	Description of Potential Failure Effect(s)	Failure Effect Class
nFAULT	MODE	False fault signaling possible. MODE setting is not affected.	В
IPROPI	nFAULT	False fault signaling possible. IPROPI feedback is inaccurate. ITRIP regulation levels, if enabled, will be lower.	В
nSLEEP	IPROPI	IPROPI feedback is inaccurate. ITRIP regulation levels, if enabled, will be lower.	В
VM	nSLEEP	SLEEP functionality is lost.	В
OUT2	VM	If OUT2 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
GND	OUT2	If OUT2 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
OUT1	GND	If OUT1 is commanded to be pulled high, short is detected and outputs are Hi-Z.	В
VM	OUT1	If OUT1 is commanded to be pulled low, short is detected and outputs are Hi-Z	В
DRVOFF	VM	Outputs are Hi-Z.	В
EN/IN1	DRVOFF	Outputs are either Hi-Z or load is in re-circulation state.	В
PH/IN2	EN/IN1	External PWM control is lost. Internal ITRIP regulation is OK. No risk of spin direction reversal.	D
DIAG	PH/IN2	Normal function as register bit is used for direction control.	D
SR	DIAG	Wrong configuration - EM performance may be affected. Load and fault response may be incorrect.	В
ITRIP	SR	Wrong configuration - EM performance may be affected. Incorrect ITRIP level for current regulation possible.	В
MODE	ITRIP	Wrong configuration possible- Both MODE and ITRIP settings are affected.	В

#### Table 4-17. Pin FMA for Device Pins Short-Circuited to VM

Pin			Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
1	nFAULT	Device damage possible.	Α
2	IPROPI	Device damage possible.	Α
3	nSLEEP	SLEEP functionality is lost.	В
4	VM	Normal function.	D
5	OUT2	If OUT2 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
6	GND	Device is powered off with driver Hi-Z.	В



Revision History www.ti.com

## Table 4-17. Pin FMA for Device Pins Short-Circuited to VM (continued)

Pin			Failure
No.	Name	Description of Potential Failure Effect(s)	Effect Class
7	OUT1	If OUT1 is commanded to be pulled low, short is detected and outputs are Hi-Z.	В
8	DRVOFF	Outputs are Hi-Z.	В
9	EN/IN1	Device damage possible.	Α
10	PH/IN2	Device damage possible.	Α
11	DIAG	Device damage possible.	Α
12	SR	Device damage possible.	Α
13	ITRIP	Device damage possible.	Α
14	MODE	Device damage possible.	Α

### **5 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

#### 

#### IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2022, Texas Instruments Incorporated